Exotic Options:
Pricing Path-Dependent single Barrier Option contracts

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Abstract

This paper discusses the basic properties of barrier options and an analytical solution for pricing such contracts. The significance of monitoring is considered, for example the difference between continuous monitoring and discrete monitoring. Pitfalls arising from a naïve application of standard option valuation techniques to barrier options are pointed out. We also discuss the practical issues related to barrier options, such as the advantages they provide to the buyer as well as to the writer, and consider practical issues behind valuation.

Key words and phrases: Barrier Options, Knock-out Options, Knock-in Options, Rebate, Path-dependant Payoff, Black & Scholes, restricted density, Reflection Principal.
1. Introduction

Barrier options are a class of exotic options which were first priced by Merton (1973). The most common approaches used to price these type of derivatives are the expectations methods and the differential equation methods. The expectations method has been worked out in detail by Rubinstein and Reiner (1991) and also Rich (1994). The expectations pricing method requires the determination of the risk-neutral densities of the underlying price as it breaches the barrier from above and below. If rebates apply then the first exit time densities through the barrier are also required. Barrier option prices are then obtained, in the usual way, by integrating the discounted barrier option pay-off function over the calculated densities. It is considered difficult to work out these densities when using the expectation approach, it is however remarkable that closed form solutions for all types of barrier options are in fact obtained.

A brief discussion of the differential equation method can be found in Wilmott (1993). The basic idea of this approach is that all barrier options satisfy the Black-Scholes partial differential equation but with different domains, expiry conditions and boundary conditions. In principal, these partial differential equations (PDE's) can be transformed to the diffusion equation and solved. Once again the analysis is complex and also requires the evaluation of integrals, but the same closed form solutions are obtained. The solution from the PDE method is of course related to the solutions from the expectation approach. Ritchken (1995) has investigated computational aspects of barrier option pricing using binomial and trinomial lattice.

In this paper, the PDE method will be adopted to show that a direct and simple analysis leads to the closed form solutions. The method employs symmetry properties of the Black-Scholes (B&S) PDE and requires little more than the well-known basic European vanilla option solutions.

2. Pricing of simple contingent claims

2.1 Asset Price Dynamics and Ito Process

The dynamics of stock price $S$ are represented by the following Ito process with a drift rate of $\mu S$ and variance rate of $\sigma^2 S^2$:

$$dS = \mu S dt + \sigma S dX$$  \hspace{1cm} (1.1)

divide both sides by $S$, to obtain the following stochastic differential equation (SDE):

$$dS / S = \mu dt + \sigma dX$$  \hspace{1cm} (1.2)

This process of stock prices, known also as the geometric Brownian motion, can be written in discrete time setting as

$$\Delta S / S = \mu \Delta t + \sigma \epsilon \Delta t$$  \hspace{1cm} (1.3)
Where $\varepsilon$ is a random sample from distribution with zero mean and a unit standard deviation. If we set $\sigma = 0$, the term involving $dX$ in equation (1.2), would drop out and we are left with ordinary differential equation (ODE)

\[
\frac{dS}{S} = \mu dt \quad \text{or} \quad \frac{dS}{dt} = \mu S
\]

Where $\mu$ is constant this can be solved exactly to give exponential growth in the value of the asset, i.e.

\[
S = S_0 \exp[\mu(t - t_0)]
\]

The random term $dX$ from equation (1.2) is known as a Weiner process which has the properties defined below. The model has the stock price growing at a constant rate $\mu$, with random fluctuations superimposed. These fluctuations are proportional to the standard deviation of the asset price and are dependant on standard normal random variable. This type of process is known as Weiner process.

**Definition 1.1** A stochastic process $X$ is called Weiner process if the following hold.\(^1\)

1. $W(0) = 0$
2. The process $W$ has independent increments, i.e. if $r < s \leq t < u$ then $W(u) - W(t)$ and $W(s) - W(r)$ are independent stochastic variables.
3. For $s < t$ the stochastic variable $W(t) - W(s)$ has a Gaussian distribution $N(0, \sqrt{t - s})$.
4. $W$ has continuous trajectories

We can write $dX$ as

\[
dX = \phi \sqrt{dt}
\]

where $\phi$ is a random variable with $N \sim (0,1)$ and a probability density function given by

\[
\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \phi^2}, \quad \text{for} \quad -\infty < \phi < \infty
\]  

(1.4)

Define the expectation operator $\xi$ by

\[
\xi[F(.)] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} F(\phi)e^{-\frac{1}{2} \phi^2} \, d\phi,
\]  

(1.5)

For any function $F$, then

\[
\xi[\phi] = 0 \quad \text{and} \quad \xi[\phi^2] = 1
\]

\(^1\) Most authors would use the letter W to associate it with the Weiner process.
It follows that from equation 1.2, the expectation and variance of $dS$ can be written as

$$
\xi[dS] = \xi[\mu S dt + \sigma S dX] = \mu S dt
$$

$$
Var[dS] = \xi[dS^2] - \xi[dS]^2 = \xi[\sigma^2 S^2 dt] = \sigma^2 S^2 dt
$$

### 2.2 Ito's Lemma

Ito's Lemma is an important result about the manipulation of random variables. While Taylor's theorem allows one to manipulate functions of deterministic variables, Ito's Lemma can be applied to manipulate functions of random variables. It relates the small change in a function of random variable to the small change of in the random variable itself.

We will use the following Ito's multiplication table\(^2\)

\[
\begin{align*}
(dx)^2 &= dt, \\
(dt)(dX) &= 0, \\
(dt)^2 &= 0,
\end{align*}
\]

If $f(S)$ is a smooth function of $S$ and we vary $S$ by small amount $dS$, then the function $f$ will also vary amount small amount $df$. Using the Taylor series expansion we can write the change of the function $f$ as:

$$
df = \frac{df}{dS} dS + \frac{1}{2} \frac{d^2 f}{dS^2} dS^2 + ..., \quad (1.6)
$$

Since $dS$ is given by equation (1.1), we square it to find that

$$
\begin{align*}
S^2 &= (\mu S dt + \sigma S dX)^2 \\
&= \sigma^2 S^2 dt + 2\sigma\mu S^2 dt dX + \mu^2 S^2 dt^2 \\
&= \sigma^2 S^2 dt + \mu^2 S^2 dt^2 \quad (1.7)
\end{align*}
$$

the first term is the largest for small $dt$ and dominates the other two terms. We are then left with

$$
S^2 = \sigma^2 S^2 dt + ...
$$

Since $dX^2 \to dt$,

$$
S^2 = \sigma^2 S^2 dt.
$$

\(^2\) See Bjork (1998) for technical details of these results.
We now substitute this result and equation 1.1 into 1.6, such that we find:

\[
 df = \frac{df}{dS} (\mu S dt + \sigma S dX) + \frac{1}{2} \frac{d^2 f}{dS^2} \sigma^2 S^2 dt
\]

\[
 df = \frac{df}{dS} \mu S dt + \frac{df}{dS} \sigma S dX + \frac{1}{2} \frac{d^2 f}{dS^2} \sigma^2 S^2 dt
\]

\[
 df = \left( \frac{df}{dS} \mu S + \frac{1}{2} \frac{d^2 f}{dS^2} \sigma^2 S^2 \right) dt + \sigma S \frac{df}{dS} dX
\]  

This is Ito's Lemma relating the small change in a function of random variable to the small change in the variable itself. The first component of the right hand side equation is deterministic component of the change in the function \( f \) and is proportional to \( dt \). The second component is a random component and is proportional to \( dt \).

The result (1.8) can be extended to a function of two variable which entails the use of partial derivatives since there are two independent random variables, i.e. \( S \) and \( t \). We can expand \( f(S + dS, t + dt) \) in a Taylor series about \((S, t)\) to get

\[
 df = \frac{\partial f}{\partial S} dS + \frac{\partial f}{\partial t} dt + \frac{1}{2} \frac{\partial^2 f}{\partial S^2} dS^2 + ...,
\]

\[
 df = \left( \frac{\partial f}{\partial S} \mu S + \frac{1}{2} \frac{\partial^2 f}{\partial S^2} \sigma^2 S^2 + \frac{\partial f}{\partial t} \right) dt + \sigma S \frac{\partial f}{\partial S} dX
\]  

\[ (1.9) \]

### 3.1 The Black-Scholes Formulation of Option Pricing

We illustrate how to use the riskless hedging principle to derive the governing partial differential equation for the price of European call. The derivation follows the approach used by Black and Scholes in their seminal paper (1973). They made the following assumption in the financial market:

(i) trading takes place continuously in time;
(ii) the riskless interest \( r \) is known and constant over time;
(iii) the asset pays no dividend;
(iv) there are no transaction costs in buying or selling the asset or the option, and no taxes;
(v) there are no riskless arbitrage opportunities;
(vi) short selling is permitted and the assets are divisible.

Let \( V(S, t) \) be the value of an option whose value depends on both \( S \) and \( t \). Using Ito's Lemma, equation (1.9), the random walk followed by \( V \) can be written
\[
dV = \left( \frac{\partial V}{\partial S} \mu S + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + \frac{\partial V}{\partial t} \right) dt + \sigma S \frac{\partial V}{\partial S} dX \tag{3.1}
\]

If we now construct a portfolio of consisting a long position of the option and a short position of the underlying asset \(-\Delta\), the value of the portfolio is

\[
\Pi = V - \Delta S \tag{3.2}
\]

The change in the portfolio in one-time step is

\[
d\Pi = dV - \Delta dS
\]

Let;

\[
\Delta = \frac{\partial V}{\partial S}
\]

Putting (1.1), (3.1) and (3.2) together, the change in the portfolio can be written as

\[
d\Pi = \left( \frac{\partial V}{\partial S} \mu S + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + \frac{\partial V}{\partial t} \right) dt + \sigma S \frac{\partial V}{\partial S} dX
- \Delta(\mu S dt + \sigma S dX)
\]

\[
= \left( \frac{\partial V}{\partial S} \mu S + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + \frac{\partial V}{\partial t} \right) dt + \sigma S \frac{\partial V}{\partial S} dX - \Delta \mu S dt - \Delta \sigma S dX
\]

Since

\[
\Delta = \frac{\partial V}{\partial S}
\]

\[
d\Pi = \left( \frac{\partial V}{\partial S} \mu S + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + \frac{\partial V}{\partial t} \right) dt + \sigma S \frac{\partial V}{\partial S} dX - \mu S \frac{\partial V}{\partial S} dt - \sigma S \frac{\partial V}{\partial S} dX
\]

by simply rearranging the above equation, we have

\[
d\Pi = (\mu S \frac{\partial V}{\partial S} - \mu S \frac{\partial V}{\partial S}) dt + (\sigma S \frac{\partial V}{\partial S} dX - \sigma S \frac{\partial V}{\partial S} dX) + \left( \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + \frac{\partial V}{\partial t} \right) dt
\]

The first two terms from the right hand side of the equation cancels each other and the random component in the equation is eliminated. This results in a portfolio whose increments is wholly deterministic:

\[
d\Pi = \left( \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 \right) dt \tag{3.3}
\]
Note the uncertainty due to $dX$ is cancelled out and $u$, the premium for risk (return on $S$), is also cancelled out. Not only that the term $d\Pi$ has no uncertainty, it is also preference free and not dependant on $u$, a parameter controlled by investors risk aversion. If the portfolio value is fully hedged, then no arbitrage implies that it must earn only risk free rate of return. We then have

$$ r\Pi dt = \left( \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 \right) dt \tag{3.4} $$

using equation (3.2)

$$ r(V - \Delta S) dt = \left( \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 \right) dt $$

since

$$ \Delta = \frac{\partial V}{\partial S} $$

$$ r(V - \frac{\partial V}{\partial S} S) dt = \left( \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 \right) dt $$

$$ (rV - rS \frac{\partial V}{\partial S}) dt = \left( \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 \right) dt $$

dividing both sides by $dt$ and rearranging the equation, we have

$$ rV = \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + rS \frac{\partial V}{\partial S} $$

finally

$$ \frac{\partial V}{\partial t} + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} \sigma^2 S^2 + rS \frac{\partial V}{\partial S} - rV = 0 \tag{3.5} $$

This is the Black-Scholes partial derivative equation and any derivative security whose price depends only on the current value of $S$ and on $t$, and which is paid for up-front must satisfy the Black-Scholes equation. The most frequent type of partial differential equation in financial problems is the parabolic equation. Equation (3.5) is called backward parabolic since the equation is linear and the signs of these particular derivatives are the same.
The price of particular derivative security is obtained by solving Equation (3.5) subject to the appropriate auxiliary conditions (terminal payoff) for the corresponding derivative security. The solution of the Black-Scholes equation with different auxiliary conditions can then provide valuation formulas for different types of derivative securities.

The term \(dX\) disappear from the PDE, which means there is no uncertainty. While the stock price evolves in an uncertain manner, when we value derivatives with respect to stock price, this uncertainty no longer exist in the pricing formula for this derivative.

The term \(u\) which is the expected rate of return on the stock also disappear from the PDE. The expected return is affected by risk preference. The more risk averse the investor, the smaller the expected return. Given that the expected return does not appear in the pricing formula for derivatives, valuation of derivatives in this framework is preference free. The solution to the differential equation is therefore the same in a risk-free world as it is in the real world. Hence, this type of valuation method are often called, risk neutral valuation relationship (RNVR).

Application of RNV sets the expected growth rate of stock equal to risk free interest rate, then discount expected payoff of option at risk free rate.

There are many solutions to (3.5) that correspond to different derivatives, \(f\), with underlying asset \(S\). In other words, without further constraints, the PDE in (3.5) does not have a unique solution.

The particular security being valued is determined by its boundary conditions of the differential equation. In the case of a European call, the value at expiry \(c(S, T) = (S - E, 0)\) serves as the final condition for the Black-Scholes PDE.

3.2 Lognormal property and stock price process

Black-Scholes (1973) assume that there are two fundamental assets: a bond with a price \(B(.)\) and a stock with a price \(S(.)\). The price of the bond and the stock are assumed to grow as follows for any \(0 \leq t \leq T\):

\[
B(t) = \exp(rt), \quad \text{and} \quad S(t) = S(0) \exp\left\{\left(\mu - \frac{1}{2} \sigma^2\right) t + \sigma w(t)\right\},
\]

where \(r\), \(u\), and \(\sigma\) are constants, and \(w(t)\) is a standard Brownian motion. The ratio of \(S(T)\) to \(S(t)\) can be written:

\[3\] See Harrison (1985) for mathematical details of Brownian motion. Brownian motion is named after the botanist Robert Brown. Brown noticed in 1827 that pollen exhibits random motion when suspended in water. The mathematics of this "Brownian motion" did not come until Bachelier (1900) and Einstein (1905).
\[ S(T) = S(0) \exp \left\{ \left( \mu - \frac{1}{2} \sigma^2 \right) T + \sigma w(T) \right\} \]

\[ S(t) = S(0) \exp \left\{ \left( \mu - \frac{1}{2} \sigma^2 \right) t + \sigma w(t) \right\} \]

\[ = \exp \left\{ \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (w(T) - w(t)) \right\} \]  (3.6)

Taking log of both sides of the above equation, we get

\[ \ln \left( \frac{S(T)}{S(t)} \right) = \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (w(T) - w(t)) \]

the increment \( w(T) - w(t) \) is distributed normal \( N(0, T - t) \), so it follow that

\[ \ln \left( \frac{S(T)}{S(t)} \right) \sim N\left( \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t), \sigma (T - t) \right) \]  (3.7)

From equation (3.6) it can also be seen that

\[ \ln(S(T)) = \ln(S(t)) + \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (w(T) - w(t)) \]

and, therefore, that

\[ \ln(S(T)) \sim N\left( \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t), \sigma (T - t) \right) \]

from equation (3.6), the terminal stock price \( S(T) \) may be written as follows:

\[ S(T) = \exp \left\{ \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (w(T) - w(t)) \right\} \]

\[ = \exp \left\{ \left( \mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma W \right\} \]  (3.8)

where \( W \equiv (w(T) - w(t)) \) is distributed as normal \( N(0, T - t) \) under the usual probability measure.
As mentioned above the price of European option at time \( t \) can be found by discounting the expected payoff of the call option (Where \( E^* \) denotes expectation taken under the risk-neutral probability measure). The expectation is taken conditional on information at time \( t \) [that is, conditional on \( S(t) \)]:

\[
c(t) = e^{-r(T-t)}E^*\left[\max(S(T) - K,0)|S(t)\right]
\] (3.9)

Now, substituting equation (3.8) into (3.9):

\[
c(t) = e^{-r(T-t)} \int_{w=-\infty}^{+\infty} \left[S(t)e^{\left(\frac{1}{2}\sigma^2\right)(T-t) + \sigma W} - K\right]^+ f_w(w)dw.
\] (3.9a)

\( f_w(w) \) is the probability density function (pdf) of \( w \). With \( W \sim N(0,T-t) \), it follows that the probability density function of \( W \) is given by

\[
f_w(w) = \frac{1}{\sqrt{2\pi \sqrt{T-t}}} e^{-\frac{1}{2} \left( \frac{w}{\sqrt{T-t}} \right)^2}
\]

Substitute this for \( f_w(w) \) in equation (3.9a) to get the call option value:

\[
c(t) = e^{-r(T-t)} \int_{w=-\infty}^{+\infty} \left[S(t)e^{\left(\frac{1}{2}\sigma^2\right)(T-t) + \sigma W} - K\right]^+ \times \frac{1}{\sqrt{2\pi \sqrt{T-t}}} e^{-\frac{1}{2} \left( \frac{w}{\sqrt{T-t}} \right)^2} dw
\]

To simplify, let \( w = \varepsilon \sqrt{T-t} \) so that \( dw = \frac{\sqrt{T-t}}{\sqrt{T-t}} d\varepsilon \) and the call option value becomes

\[
c(t) = e^{-r(T-t)} \int_{\varepsilon=-\infty}^{+\infty} \left[S(t)e^{\left(\frac{1}{2}\sigma^2\right)(T-t) + \varepsilon \sqrt{T-t}} - K\right]^+ \times \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} d\varepsilon
\]

let \( \varepsilon_0 \) be such that \( S(t)e^{\left(\frac{1}{2}\sigma^2\right)(T-t) + \varepsilon \sqrt{T-t}} - K \) = 0, then

\[
\varepsilon_0 = \frac{1}{\sigma \sqrt{T-t}} \left\{ \ln \left( \frac{K}{S(t)} \right) - \left( r - \frac{1}{2} \sigma^2 \right)(T-t) \right\}
\]
The formula for \( c(t) \) simplifies slightly because the integrand\(^4\) is identically zero when \( \varepsilon < \varepsilon_0 \)

\[
c(t) = e^{-(T-t)} \int_{\varepsilon=\varepsilon_0}^{+\infty} \left( S(t) e^{\left( \mu - \frac{1}{2} \sigma^2 \right) (T-t) + \sigma \varepsilon \sqrt{T-t} } - K \right) \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

We may split the integrand (and hence the integral ) into two components:

\[
c(t) = e^{-(T-t)} \int_{\varepsilon=\varepsilon_0}^{+\infty} S(t) e^{\left( \mu - \frac{1}{2} \sigma^2 \right) (T-t) + \sigma \varepsilon \sqrt{T-t} } \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

\[
- Ke^{-(T-t)} \int_{\varepsilon=\varepsilon_0}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

Collect terms and simplify:

\[
c(t) = S(t) \int_{\varepsilon=\varepsilon_0}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2 (T-t) + \sigma \varepsilon \sqrt{T-t} - \frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

\[
- Ke^{-(T-t)} \int_{\varepsilon=\varepsilon_0}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

The exponent in the integrand of the first term is scaled perfect square satisfying

\[
- \frac{1}{2} \sigma^2 (T-t) + \sigma \varepsilon \sqrt{T-t} - \frac{1}{2} \varepsilon^2 = -\frac{1}{2} \left( \varepsilon - \sigma \sqrt{T-t} \right)^2 = -\frac{1}{2} \varepsilon'{}^2,
\]

where \( \varepsilon' \equiv \varepsilon - \sigma \sqrt{T-t} \). Now substitute this into the first integral to simply the expression for \( c(t) \):

\[
c(t) = S(t) \int_{\varepsilon=\varepsilon_0}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon'{}^2} \, d\varepsilon' - ke^{-(T-t)} \int_{\varepsilon=\varepsilon_0}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2} \varepsilon^2} \, d\varepsilon
\]

\(^4\) The integrand is that part that of the integral that falls between the \( \int \) and the \( d\varepsilon \)
The integrands are normal standard pdf's. Therefore, the integrals involve normal standard normal cdf's. The option value $c(t)$ may now be written in terms of the cumulative standard normal function $N(.)$ as follows:

$$c(t) = S(t) \left[ 1 - N(\varepsilon_0 - \sigma\sqrt{T-t}) \right] - Ke^{-r(T-t)} \left[ 1 - N(\varepsilon_0) \right].$$

From the property of the cumulative standard Normal function: $[1 - N(z)] = N(-z)$ This may be used to simplify $c(t)$:

$$c(t) = S(t)N(-\varepsilon_0 + \sigma\sqrt{T-t}) - Ke^{-r(T-t)}N(-\varepsilon_0)$$

By algebraic manipulations, one can show that if

$$\varepsilon_0 = \frac{1}{\sigma\sqrt{T-t}} \left\{ \ln \left( \frac{K}{S(t)} \right) - \left( r - \frac{1}{2}\sigma^2 \right)(T-t) \right\},$$

then

$$-\varepsilon_0 = \frac{\ln \left( \frac{S(t)}{K} \right) + \left( r - \frac{1}{2}\sigma^2 \right)(T-t)}{\sigma\sqrt{T-t}},$$

and

$$-\varepsilon_0 + \sigma\sqrt{T-t} = \frac{\ln \left( \frac{S(t)}{K} \right) + \left( r + \frac{1}{2}\sigma^2 \right)(T-t)}{\sigma\sqrt{T-t}},$$

If we label the latter two terms and $d_2$ and $d_1$ respectively, you get the Black-Scholes formula for the price of a standard European call on a non dividend-paying stock:

$$S(t)N(d_1) - e^{-r(T-t)}KN(d_2),$$

where

$$d_1 = \frac{\ln \left( \frac{S(t)}{K} \right) + \left( r + \frac{1}{2}\sigma^2 \right)(T-t)}{\sigma\sqrt{T-t}}$$

and

$$d_2 = -d_1 - \sigma\sqrt{T-t}.$$
The above call price formula can be interpreted using the language of probability. First, \( N(d_2) \) is seen as the probability of the call being in-the-money at expiry and so \( KN(d_2) \) can be interpreted as the risk neutral expectation of the payment made by the holder of the call option at expiry on exercising the option. Second, \( S(t)e^{r(t-T)}N(d_1) \) is the risk neutral expectation of the asset price at expiry conditional on the call being in-the-money. Hence, the expectation of the call value at expiry is

\[
= S(t)N(d_1) - e^{-r(T-t)} KN(d_2),
\]

which is then discounted by the factor \( e^{-r(T-t)} \) in the risk neutral world to give the present value of the call.

4.1 Barrier Options

Options with the barrier feature, commonly called barrier options, are considered to be one of the simplest types of path-dependent options. The unique feature is that the payoff depends not only on the final price of the underlying asset but also on whether or not the underlying asset price has reached (one-touch) some barrier level during the life of the option. An out-barrier option (knock-out option) is one where the option is nullified prior to expiration if the underlying asset price touches the barrier. The option holder may be compensated by a rebate payment for the cancellation of the option. An in-barrier option (knock-in) option is barrier option type which comes into play if the asset price hits or crosses the predefined barrier level. When the barrier is approached from below, the barrier option is called an up-option; otherwise it is called down-option. One can identify eight type of European barrier options, such as down-in calls, up-in calls, down-out calls, up-out calls. And similar four types of options for the European barrier put options.

All these options are called standard or vanilla barrier options. The attractiveness of barrier options is that they are cheaper than their corresponding vanilla options, as the sum of the premiums of a knock-in and its corresponding knock-out is always the same as the premium of their corresponding vanilla option if there are no rebates.

4.2 Vanilla barrier options

Another name for barrier type options is also a trigger option. This is because the payoff depends critically on whether a pre-specified barrier or a trigger is touched during the life of the option. If the barrier is breached during this time, the holder is entitled to receive a European option. Otherwise, the holder gets a rebate at the maturity of the option. This kind of barrier is known as knock-in barrier option, or simply knock-in. Given the underlying asset price, the barrier level can be placed above or below it. If the barrier is below the underlying price, the knock-in option is called a down knock-in option (DI - for down and in option). The payoff of a down knock-in option (PDI) can be formally given as
\[
PDI = \max \{[\omega S(t^*) - \omega K, 0] \} S(t) > H
\]
and \( S(T) \leq H \), for some \( t < T \leq t^* \), \hspace{1cm} (4.2a)

or
\[
PDI = Rm(\tau) \text{ if } S(t) > H \text{ and } S(T) > H, \text{ for all } t < T \leq t^*,
\] \hspace{1cm} (4.2b)

Where \( t, \text{ and } t^* \) are the current and expiration time of the option respectively; \( H \) is the knock-in boundary of the option or the constant barrier level. \( K \) is the strike price of the option; \( \omega \) is a binary operator (1 for a call and -1 for a put). \( Rm(\tau) \) is the rebate of the barrier option paid at maturity if the barrier is not touched.

Below we also so define the payoff for remaining vanilla barrier types such as up-and-in (PUI), down-and-out (PDO). For up-and-out (PUO) payoff see Zhang (1998).

The payoff of an up-and-in barrier option (PUI) is given formally as;
\[
PUI = \max \{[\omega S(t^*) - \omega K, 0] \} S(t) < H
\]
and \( S(T) \geq H \), for some \( t < T \leq t^* \), \hspace{1cm} (4.2c)

or
\[
PUI = Rm(\tau) \text{ if } S(t) < H \text{ and } S(T) < H, \text{ for all } t < T \leq t^*.
\]

The Payoff of a down and knock out barrier option or simply down-and-out is given;
\[
PDO = \max \{[\omega S(t^*) - \omega K, 0] \} S(t) > H
\]
and \( S(T) > H \), for some \( t < T \leq t^* \), \hspace{1cm} (4.2c)

or
\[
PDO = R(T) \text{ if } S(t) > H \text{ and } S(T) \leq H, \text{ for all } t < T \leq t^*.
\]

\( R(T) \) is in this case also the rebate function which is time dependant. \( R(T) \) is most often an increasing function of time starting from zero, or \( R'(T) > 0 \) and \( R(0) = 0 \). The rebate defined in (4.2c) is called non-deferred rebate, implying that the rebate is paid as soon as the barrier is reached. The rebate can also be deferred, that is, the rebate payment can be postponed until maturity.
4.2.1 Path Independence and Path Dependence

A security is path-independent if its value at a given point in time depends on the so-called state-of-the-world at the time, and now on how the world evolved to that state. For example, the premium of European option depends on the price and the return volatility of the underlying at a given point in time, but is independent of the actual price history that transpired prior to that time. Barrier options are dependant on price history for determining if a barrier has been hit or not. For an out-option, this type of dependency is theoretically no different than the path-dependency inherent in the early exercise of an American option. A non-linear barrier option exist for an American option, defined at time $t$ by the critical price $S_t$ at which the investor should exercise. In practise this barrier is subjective, to the extent that the investor needs to specify volatility before the American barrier can be identified. Also, the rational investor would exercise, but is not required to do so, whereas the breaching of the barrier triggers a contractual provision in a knock-out or knock-in option.

Financial engineers are concerned with yet another type of path dependence - whether and how backward recursion can be used for pricing. Backward recursion refers to the methods such as Cox-Ross-Rubinstein. This is of interest because backward recursion is flexible and efficient when compared to Monte Carlo simulations. In order to use backward recursion one requires the security (contingent claim) being priced be path-independent (in a weak sense). Fortunately, barrier options are path-independent in this sense.

4.3 Reflecting barrier

A Brownian motion with reflecting barrier is also called Brownian motion reflected about some particular point. A Brownian motion $X(t)$ reflected about the line $x = b$ is given as follows.

\[
\tilde{X}(t) = \begin{cases} 
X(t) & \text{for } t < T_b \\
2b - X(t) & \text{for } t > T_b 
\end{cases}
\]

**Figure 1.1** Simulated asset prices with a fixed barrier level of 115.
The well-known result about the reflecting barrier is the reflection principle which states that for every sample path with $X(T) > b$ there are two sample paths $\tilde{X}(T)$ and $X(T)$ with the same probability of occurrence. Because of the symmetry with respect to $b$ of a Brownian motion $X(t)$ starting at $b$, the "probability" of doing this is the same as the "probability" of travelling from $b$ to the point $2b - X(t)$. The reason for this is that, for every bath which crosses level $b$ and is found at time $t$ at a point below $b$, there is a shadow path $\tilde{X}(t)$ obtained from the reflection about the level $b$ which exceeds this level at time $t$, and these two paths have the same probability. The actual probability for the occurrence of any particular path is zero. With the argument stated above, we can write the equation of the reflection principle as follows:

$$P[T_b < t, X(t) < b] = P[T_b < t, X(t) > b] = P[X(t) > b].$$

Where $T_b$ stands for the time when the reflecting barrier $b$ is first touched and $P$ is the probability. The reflection principle can be used to find the first passage time. The solution of the density functions for the Brownian motion with a reflecting barrier can be found in several textbooks in financial mathematics. 

### 4.4.1 Unrestricted distribution and absorbing barrier

Let $g$ stand for the annual continuous dividend yield on the underlying asset. The stochastic process which governs the underlying asset price movement given in (1.1) becomes

$$dS = (\mu - g)Sdt + \sigma Sdz(t),$$

where all the parameters are the same as equation (1.1) except for incorporating the continuous dividend payout. The solution to the above SDE is given below

$$S(\tau) = S \exp[v\tau + \sigma w(\tau)],$$

where $\tau = t^* - t$, $[t, t^*]$ stand for current time and expiration time of the option, respectively, $v = r - g - \sigma^2 / 2$, and $w(\tau)$ is standard Gauss-Weiner process (note here that we have changed the notation slightly).

We know that $X_\tau = \ln[S(\tau)/S]$ is the log-return of the underlying asset, then the density function of $X_\tau$ is normally distributed with mean $v\tau$ and variance $\sigma^2 \tau$. Its pdf is then given by:

---

5 For example, see: Yue-Kuen Kwok, Mathematical Models of Financial Derivatives (1998)
Also, see: Peter James, Option Theory (2003)
$$f(x) = \frac{1}{\sigma \sqrt{2\pi \tau}} \exp \left[ -\frac{(x - \nu \tau)^2}{2\sigma^2 \tau} \right].$$  \hspace{1cm} (4.2.1)

Below we provide the result from Cox and Miller (1965) for the density function of a Brownian process with an absorbing barrier. An absorbing barrier is a barrier which upon touching, all the particles vanish.

$$f(x) = \frac{1}{\sigma \sqrt{2\pi \tau}} \exp \left[ -\frac{(x - \nu \tau)^2}{2\sigma^2 \tau} \right] - e^{2av/\sigma^2} \exp \left[ -\frac{(x - 2a - \nu \tau)^2}{2\sigma^2 \tau} \right] \text{ for } x < a,$$  \hspace{1cm} (4.2.1a)

### 4.4.2 Restricted Distributions

From the specification of the payoff of a brier option, we know that in order to price it, we certainly need another density function conditioned on whether the barrier is reached during the life of the option. Define:

$$M^*_t = \max \{ S(s) \mid s \in [t, t^*] \},$$ \hspace{1cm} (4.3a)

and

$$m^*_t = \min \{ S(s) \mid s \in [t, t^*] \},$$ \hspace{1cm} (4.3b)

where $x \in X$ stands for that $x$ belongs to $X$; $[t, t^*]$ stands for the set of real numbers starting from $t$ and ending at $t^*$. max and min represent the functions giving the maximum and the minimum of a set of numbers, respectively.

The two variables given in (4.3a) and (4.3b) are the maximum and minimum of all underlying asset prices within the life of the option. We can express these in terms of log-returns:

$$Y_t = \ln(M^*_t / S) \quad \text{and} \quad y_t = \ln(M^*_t / S),$$ \hspace{1cm} (4.3c)

let $T_a$ stand for the time the underlying asset price first reaches an up barrier $U$. The following always hold:
\[ P_r(T_a > \tau) = P_r(M^*_{i+1} < U) = P_r(Y_r < a), \quad (4.4a) \]

and

\[ P_r(T_a \leq \tau) = P_r(M^*_{i+1} \geq U) = P_r(Y_r \geq a), \quad (4.4b) \]

Equation (4.4a) shows that the barrier is never hit within the life of the option since the first time barrier is breached is after the expiration time of the option. This is equivalent to the fact that the maximum value of the underlying asset price within the life of the option is always below the barrier in a probabilistic sense. Equation (4.4b) is the complement of (4.4a), and implies that the barrier is touched within the life of the option since the first time the barrier is hit is during the life of the option.

The joint-cumulative distribution between the log-return of the underlying asset and the transferred maximum given in (4.3c) is given as follows [see Harrison (1985)] for \( x \), \( y \geq 0 \):

\[ F(X_r \leq x, Y_r \leq y) = N\left(\frac{x - vt}{\sigma \sqrt{\tau}}\right) - e^{2yv/\sigma^2} N\left(\frac{x - 2y - vt}{\sigma \sqrt{\tau}}\right), \quad (4.5) \]

where \( N(.) \) is the cumulative function of a standard normal distribution. The joint-cumulative function in (4.5) is equivalent to the following

\[ F(X_r \leq x, Y_r < y) = N\left(\frac{x - vt}{\sigma \sqrt{\tau}}\right) - e^{2yv/\sigma^2} N\left(\frac{x - 2y - vt}{\sigma \sqrt{\tau}}\right), \quad (4.5a) \]

Equation (4.4a) and (4.5a) together imply that (4.5a) is the cumulative function of the log-return of the underlying asset conditional on the fact that the barrier is never touched within the life of the option. Differentiating (4.5a) with respect to \( x \) yield the density function of the log-return of the underlying asset conditional on the fact that the barrier \( U \) is never touched within the life of the option as:

\[ \phi(x \mid Y_r < a) = f(x) - e^{2vrt/\sigma^2} f(x - 2a), \quad (4.5b) \]

or

\[ \phi(x \mid Y_r < a) = f(x) - \left(\frac{U}{S}\right)^{2v/\sigma^2} f(x - 2a) \text{ for } x < a, \quad (4.5c) \]

and

\[ \phi(x \mid Y_r < a) = 0 \text{ for } x \geq a, \]

where \( f(x) \) is the unrestricted density function of the log-return of the underlying asset given in (4.2.1). The restricted density function given in (4.5b) or (4.5c) is exactly the same as the solution to the Brownian motion with an absorbing barrier \( a > 0 \) given in (4.2.1a).

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The complement of being always below the barrier is not always being above or at the barrier, because it is possible that the barrier is reached and the price ends up below. The density function that the barrier is touched can be obtained from the following identity.

\[ \phi(x \mid Y_t \geq a) + \phi(x \mid Y_t < a) = f(x) \]  

(4.5d)

This equation can be interpreted as the summation of the probability when the barrier is touched and the probability when the barrier is never touched within the live of the option, and this is the same as the unrestricted density given in (4.2.1a).

### 4.5.1 Distribution of the first passage time

The first passage time to a particular point on the path of the underlying asset price is the first time that this particular point is first reached. The joint probability that \( x = y = a > 0 \) for an up-barrier can be obtained using (4.4a) and (4.5)

\[ P(X_t \leq a, Y_t \leq a) = P(X_t \leq a, T_a > \tau) \]

\[ = N\left(\frac{a - vt}{\sigma \sqrt{\tau}}\right) - e^{2a\sigma^2 / \tau} N\left(\frac{-a - vt}{\sigma \sqrt{\tau}}\right), \]  

(4.6)

if the drift term \( \nu = r - g - \sigma^2 / 2 \geq 0 \), the density function of the first passage time from zero to the transferred barrier point \( a = \ln(U/S) > 0 \) can be obtained by differentiating (4.6) with respect to the time to maturity.

\[ h(T \mid a > 0) = \left[ -\frac{\partial}{\partial \tau} F(X_t \leq a, Y_t \leq a) \right]_{\tau = T} \]

\[ = \frac{a}{\sigma \sqrt{2\pi T^3}} \exp\left[ -\frac{(a - \nu T)^2}{2\sigma^2 T} \right], \]  

(4.6a)

equation (4.6a) is the distribution of the first passage time.

### 5.1 Pricing standard barrier options

One of the oldest barrier option types such as down-and-out call options were first made available in the U.S. market from 1967. The corresponding valuation formula for these options was driven by Merton (1973). A decade later Bergman (1983) developed a framework for pricing path-dependant claims such as barrier options, and Cox and Rubinstein (1985) used their down-and-out formula to price fixed income securities with embedded characters. Rubinstein and Reiner (1991) also contributed detailed results for all barrier option types with the assumption that the underlying asset price follows lognormal process.
The expected payoffs of in and out barrier options can be calculated in the same way as in vanilla options with the only exception that the restricted density function shown above is used. Using a risk-neutral evaluation relationship, one can obtain barrier option prices by discounting the expected payoffs at the risk-free rate of return. The barrier option is however also affected by the relative magnitude of the strike price and the barrier level. For a down-and-in call with a strike price $K$ greater than the barrier level $H$ and without any rebate, the value of the call can be found by integrating the payoff of a vanilla call option with the restricted density function for all possible underlying asset price starting from the strike price $K$ to infinity.

If however the strike price is below or lower the barrier, the payoff of the down-and-in call barrier option includes two parts: the integration of the payoff function of a vanilla call option with the restricted density functions given in (5.1a) for all possible underlying asset prices starting from the barrier $H = L$ to infinity, and the integration of the same payoff function with the density function given in (5.1b) for all $S$ starting from the strike price $K$ to the barrier $H = L$.

\[
\phi(x \mid Y_t \leq b) = e^{b\nu / \sigma^2} f(x - 2b) = \left( \frac{L}{S} \right)^{2\nu / \sigma^2} f(x - 2a) \text{ for } x > b \quad (5.1a)
\]

and

\[
\phi(x \mid Y_t > b) = f(x) \text{ for } x \leq b, \quad (5.1b)
\]

where $b = \ln(L/S)$ and $L$ stands for a down-barrier $L < S$. (5.1a) is the restricted density function of the underlying asset log-return under the condition that the down-barrier is touched within the options lifetime.

### 5.2 Down-and-in barrier call option

The payoff of a down-an-in barrier call option can be divided in two parts; one part including the payoff of the corresponding vanilla option if the barrier is reached any time within the life of the option, and the rebate if the barrier is never reached. Within the life of the option. Lets first consider the case where the strike is greater than the barrier level ($K > H$). The value of down-and-in call option (VDIC) without any rebate if the barrier is reached is readily obtained by discounting it is expected payoff given in equation (4.2a) at the risk-free rate of return:

\[
VDIC = \left( \frac{H}{S} \right)^{2\nu / \sigma^2} \left\{ \left( \frac{H^2}{S} \right) - Ke^{-\nu T} N \left[ d_{1ba} \left( \frac{H^2}{S}, K \right) \right] - e^{-\nu T} N \left[ d_{ba} \left( \frac{H^2}{S}, K \right) \right] \right\},
\]

where
\[ d_{bs}(S, K) = \frac{\ln(S / K) + (r - g - \sigma^2 / 2)\tau}{\sigma\sqrt{\tau}} = \frac{\ln(S / K) + \nu\tau}{\sigma\sqrt{\tau}}, \]

\[ d_{1bs}(S, K) = d_{bs}(S, K) + \sigma\sqrt{\tau} \]

d\(_{bs}, d\(_{1bs}\) are an extended version Black-Scholes parameters we have already seen above. We can also extend the Black-Scholes solution for the call price and use this formula to give an alternative compact formula for the down-and-in barrier call option;

\[ C_{bs}(S, K) = \omega Se^{-\nu t} N[\omega d_{1bs}(S, K)] - \omega Ke^{-\nu t} N[\omega d_{bs}(S, K)] \]

The value of down-and-in call barrier option can then also be written in form

\[ VDIC = \left( \frac{H}{S} \right)^{2v / \sigma^2} C_{bs}\left( \frac{H^2}{S}, K \right), \tag{5.2} \]

The formula (5.2) gives the value of a down-and-in call option without any rebate when the strike price is greater than the barrier. In the case when the strike is lower than the barrier, the whole integration ranges must then be divided into sub-ranges. For example, the integration range \((K, \infty)\) into \((K, H)\) and \((H, \infty)\) because the corresponding density functions are different into these sub-ranges. For the range \((H, \infty)\) we can obtain the value of the option in this up portion (VDNUP)

\[ VDNUP = \left( \frac{H}{S} \right)^{2v / \sigma^2} \left\{ \left( \frac{H^2}{S} \right) e^{-\nu t} N\left[ d_{1bs}\left( \frac{H^2}{S}, K \right) \right] - Ke^{-\nu t} N\left[ d_{bs}\left( \frac{H^2}{S}, K \right) \right] \right\}, \]

\[ = \left( \frac{H}{S} \right)^{2v / \sigma^2} \left\{ C_{bs}\left( \frac{H^2}{S}, H \right) + (H - K)e^{-\nu t} N\left[ d_{bs}\left( H, S \right) \right] \right\}, \tag{5.3} \]

Where \(C_{bs}\) is again the extended Black-Scholes formula given above. Since the range \((K, H)\) is equivalent to the difference of the two ranges \((-\infty, H)\) and \((-\infty, K)\), we can obtain the value of the down-and-in call for the range \((K, H)\)

\[ VDNIC = P_{bs}(S, K) - P_{BS}(S, H) + (H - K)e^{-\nu t} N\left[ -d_{bs}\left( S, H \right) \right], \tag{5.4} \]

where
\[ P_{bs}(S,K) \] is the Black-Scholes formula for vanilla European put option. The value of the down-and-in option without any rebate is therefore the sum of the values of the options given in (5.3) and (5.4). From the above analysis, the pricing formula of a down-and-in option depends on whether \( K > H \) or \( K < H \). In order to obtain a general formula to cover both situations, one can use an indicator \( B_{H>K} \) which equals one when \( H > K \), and zero if otherwise. Given the above indicator, we can express the price of down-and-in call option (DINC) without rebate:

\[
\begin{align*}
DINC &= \left( \frac{H}{S} \right)^{2v/\sigma^2} \left( C_{bs} \left[ \frac{H^2}{S}, \max(H,K) \right] \right) \\
&+ \left[ \max(H,K) - K \right] e^{-rt} N\left\{ d_{bs} \left[ \frac{H^2}{S}, \max(H,K) \right] \right\} \\
&+ \left\{ P_{bs}(S,K) - P_{bs}(S,H) + (H - S)e^{-rt} N\left[ -d_{bs}(S,H) \right] \right\} B_{H>K}, \quad (5.6)
\end{align*}
\]

Where \( \max(H,K) \) is the function which gives the larger of the two numbers \( H \) and \( K \), and other parameters are the same as in (5.3) and (5.4). When \( K > H \), the pricing formula given is (5.6) becomes the same as (5.2) because \( \max(H,K) = K \), and \( B_{H>K} = 0 \). We can also check when \( K < H \), \( \max(H,K) = H \), \( B_{H>K} = 1 \), the pricing formula (3.6) is the sum of the two pricing formulas given in (5.3) and (5.4) and the sum represents the value of the down-and-in call option when there is no rebate.

We now continue to price down-and-call option by using numerical example and with the assumption that the down barrier is touched. This implies that the rebate is zero.

To find the price of down-and-in barrier call option, consider the following parameter: strike price \( K = £98 \), spot price = £100, barrier level of \( H = £95 \), interest rate \( r = 8\% \), the yield of the underlying asset \( g = 3\% \) and volatility of the underlying asset = 20%.

Substituting \( S = £100 \), \( K = £98 \), \( H = £95 \), \( w = 0.20 \), \( r = 0.08 \), \( g = 0.03 \), and \( t = 0.5 \) into (5.6) yields

\[
\begin{align*}
v &= r - g - \sigma^2 / 2 = 0.8 - 0.03 - (0.20^2 / 2) = 0.03, \\
(H^2 / S) &= (95^2 / 100) = 90.25, \\
\max(H,K) &= \max(95,98) = 98,
\end{align*}
\]
\[ d_{hr}\left(\frac{H^2}{S}, K\right) = \ln\left[\frac{(H^2 / 2) / K}{\sigma \sqrt{\tau}}\right] + \nu \tau = -0.4765, \]

\[ d_{hrs}\left(\frac{H^2}{S}, K\right) = d_{hr}\left(\frac{H^2}{S}, K\right) + \sigma \sqrt{\tau} = -0.3351 \]

Since \( K = \£98 > \£95 = H \), the call option price \( B_{H > K} = 0 \). We can then find the down-and-in call price from (5.6) as follows:

\[ DINC(K = 98) = \left(\frac{H}{S}\right)^{2 \nu \sigma^2} C_{hrs}\left(\frac{H^2}{S}, K\right) = \left(\frac{H}{S}\right)^{2 \nu \sigma^2} \left\{ \left(\frac{H^2}{S}\right) e^{-g^2} N\left[d_{hrs}\left(\frac{H^2}{S}, K\right)\right] - Ke^{-g^2} N\left[d_{hr}\left(\frac{H^2}{S}, K\right)\right]\right\}, \]

\[ 0.95^{2 \times 0.03 / 0.20^2} \left[ 90.25 e^{-0.03 \times 0.5} N(-0.3351) - 98 e^{-0.08 \times 0.5} N(-0.4765) \right] = \£2.731 \]

when the strike price \( K = \£92 \), max \( (H, K) - \) max \( (95, 92) = \£ 95 \), \( B_{H > K} = 1 \), and all the terms in (5.6) and nonzero.

Substituting \( S = \£100 \), \( K = \£92 \), \( B_{H > K} = 1 \), \( \sigma = 0.20 \), \( r = 0.08 \), \( g = 0.03 \) and \( t = 0.50 \) into (5.6) yields:

\[ d_{hrs}\left[\frac{H^2}{S} \text{max}(H, K)\right] = \ln\left[\frac{(H^2 / S) / H}{\sigma \sqrt{\tau}}\right] + \nu \tau = -0.2566, \]

\[ d_{hrs}\left[\frac{H^2}{S} \text{max}(H, K)\right] = d_{hr}\left(\frac{H^2}{S}, K\right) + \sigma \sqrt{\tau} = -0.1152, \]

\[ P_{hs}(S, K) = -S\left[e^{-g^2} N\left[-d_{hrs}(S, K)\right]\right] + ke^{-g^2} N\left[-d_{hr}(S, K)\right] = 1.5801, \]

\[ P_{hs}(S, H) = -Se^{-g^2} N\left[-d_{hrs}(S, H)\right] + He^{-g^2} N\left[-d_{hr}(S, H)\right] = 2.4896 \]

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Thus the value of the down-and-in call option is

\[
DINC = \left( \frac{95}{100} \right)^{2 \times 0.03 / 0.2^2} \left[ 3.9816 + (95 - 92)e^{-0.08 \times 0.5} N(-0.2566) \right]
+ \left[ 1.5801 - 2.4896 + (95 - 92)e^{-0.08 \times 0.05} N(-0.4689) \right] = £4.863
\]

the price of the down-and-in barrier call option can also be incorporated in the case when the barrier is never touched and the option pays some rebate. (the present value of this rebate is given above). For compact solutions for all remaining types of barrier options can be found under Haug (1998).

The value of the rebate at the option maturity can be obtained by integrating the restricted density function below from which the down barrier \( H = L \) to infinity.

\[
\phi(x \mid Y_r > b) = f(x) - \left( \frac{L}{S} \right)^{2v / \sigma^2} f(x - 2b) \quad \text{for } x > b,
\]

\[
E\{PUKI|S(t) < H\} \text{ and } S(T) < H \quad \forall \ t < T < t^*
\]

\[
= Rm(\tau) \left\{ N[d_{bs}(S, H)] - \left( \frac{H}{S} \right)^{2v / \sigma^2} N[d_{bs}(H, S)] \right\}, \quad (5.7)
\]

The present value of the rebate is obtained by discounting (5.7) at the risk free rate \( r \):

\[
RBDI = e^{-rt} Rm(\tau) \left\{ N[d_{bs}(S, H)] - \left( \frac{H}{S} \right)^{2v / \sigma^2} N[d_{bs}(H, S)] \right\}, \quad (5.8)
\]

RBDI is the present value of the rebate for down-and-in call option.
The price of down-and-in call option (PDIC) can now be expressed using (5.6) and (5.8):

\[ PDIC = DINC + RBDI \]

Where RBDI and DINC are given in equations (5.6) and (5.8) respectively.

To find the present value of the rebate when the rebate is paid £1.5 at maturity if the barrier is not touched within the live of the call option from the numerical example above, substituting

\[ Rm(0.5) = 1.5, \quad S = £100, \quad H = £95, \quad \text{sigma} = 0.20, \quad r = 0.08, \quad g = 0.03, \quad \text{and} \quad t = 0.50 \]

Into equation (5.8) yields

\[
\begin{align*}
\frac{1.5}{200} + 0.03(0.5) \frac{\ln(100/95)}{0.20\sqrt{0.50}} &= 0.4688, \\
\frac{1.5}{200} + 0.03(0.5) \frac{\ln(95/100)}{0.20\sqrt{0.50}} &= -0.2566,
\end{align*}
\]

\[ RBDI = 1.5e^{-0.08 \times 0.05} \left[ N[\frac{0.4688}{\text{σ}\sqrt{\tau}}] - \left( \frac{95}{100} \right)^{2 \times 0.03 / \text{σ}^2} N[-0.2566] \right] = £0.449 \]

we can now find the price of the down-and-in call option when the rebate is paid £1.5 at maturity if the barrier is not touched within the live of the option

The down-and-in call option price with strike price \( K = 92 \)

\[ = DINC(K = 92) + RBDI = 4.862 + 0.449 = £5.312 \]

An important issue of pricing barrier options is whether the barrier crossing is monitored in continues time. Most models assume continues monitoring of the barrier. In other words, in the models a knock-in or knock-out occurs if the barrier is reached at any instance before the maturity of the contract, mainly because this leads to analytical solutions; see for example Merton (1973), Heynen & Kat (1994a,1994b) and kunitomo & Ikeda (1992) for various formulae for continuously monitored barrier options under the classical Brownian motion framework; see Kou & Wang (2001) for continuously monitored barrier options under a jump diffusion framework.

However in practice most, if not all, barrier options traded in markets are discretely monitored. In other words, they specify fixed times for monitoring of the barrier (typically daily closings).
Besides practical implementation issues, there are some legal and financial reasons why discretely monitored barrier options are preferred to continuously monitored barrier options. For example, some discussions in trader's literature ("Derivatives Week", may 29th, 1995) voice concern that, when the monitoring is continuous, extraneous barrier breach may occur in less liquid markets while the major western markets are closed, and may lead to certain arbitrage opportunities.

Although discretely monitored barrier options are popular and important, pricing them is not as easy as that of their continuous counterparts for three reasons. (1) There are essentially no closed solutions, except using \( m \)-dimensional normal distribution function (\( m \) is the number of monitoring points), which can hardly be computed easily if, for example \( m > 5 \); see Reiner (2000). (2) Direct Monte Carlo simulation or standard binomial trees may be difficult, and can take hours or even days to produce accurate results; see Broadie, Glasserman and Kou (1999). (3) Although the Central Limit Theorem asserts that, as \( m \rightarrow \infty \), the difference between continuously and discretely monitored barrier options should be small, it is well known in the traders literature that numerically the difference can be surprisingly large, even for large \( m \).

To give a feel for the accuracy of these models, see Table 1.1. This is reproduced with permission from Brodie, Glasserman and Kou (1997). The numerical results shown in Table 1.1 suggest that, even for daily monitored discrete barrier options, there can still be big differences between the discrete prices and the continuous prices.

**Table 1.1**
Up-and-out Call option price results, with \( m = 50 \) (daily monitoring) and following parameters:

\[
\begin{align*}
S(0) &= 110 \\
K &= 100 \\
\sigma &= 0.30 \text{ per year} \\
r &= 0.1, \text{ and} \\
T &= 0.2 \text{ year, which represents roughly 50 trading days.}
\end{align*}
\]

<table>
<thead>
<tr>
<th>Barrier</th>
<th>Continuous Barrier</th>
<th>Corrected Barrier</th>
<th>True</th>
<th>Relative error</th>
</tr>
</thead>
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<tr>
<td>155</td>
<td>12.775</td>
<td>12.905</td>
<td>12.894</td>
<td>0.1</td>
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<tr>
<td>150</td>
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<td>12.448</td>
<td>12.431</td>
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<tr>
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<td>11.707</td>
<td>11.684</td>
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<td>10.581</td>
<td>10.551</td>
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<td>8.994</td>
<td>8.959</td>
<td>0.4</td>
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<td>130</td>
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<td>6.959</td>
<td>6.922</td>
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<td>4.616</td>
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<tr>
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<td>0.819</td>
<td>0.807</td>
<td>1.5</td>
</tr>
</tbody>
</table>

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References


James, P., (2003), *Option Theory*, John Wiley & Sons Ltd


